

TMR Bipolar Switch

#### **General Description**

The TMR1201 is a digital latching bipolar magnetic switch that integrates TMR and CMOS technology in order to provide a magnetically triggered digital switch with high sensitivity, high speed, and low power consumption. It integrates a push-pull half-bridge TMR magnetic sensor and CMOS signal processing circuitry within the same package. Designed for use in high accuracy applications, this device includes an on-chip TMR voltage generator for precise magnetic sensing, TMR voltage amplifier and comparator, a Schmitt trigger to provide switching hysteresis for noise rejection, and CMOS push-pull output. An internal band gap regulator is used to provide temperature compensated supply voltage for internal circuits, and it allows a wide range of operating supply voltages. The TMR1201 features accurate switching points, fast response, a wide operating temperature range, and excellent ESD immunity. It is available in two packaging form factors: SOT23-3 (P/N TMR1201S), or TO-92S (P/N TMR1201T).

#### **Features and Benefits**

- Tunneling Magnetoresistance (TMR) Technology
- Bipolar Latching Operation
- Low Operate Points for High Sensitivity
- Very Low Power Consumption
- Compatible with a Wide Range of Supply Voltages
- Excellent Thermal Stability
- High-Speed Detection and High Frequency Response
- High ESD Tolerance

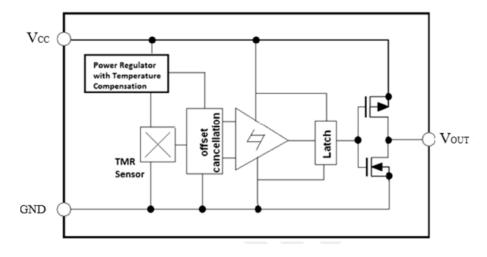
### Applications

- Utility Meters including Water, Gas, and Heat Meters
- Solid State Switching
- Speed Sensing
- Rotor Position Sensing
- Linear Displacement Sensing

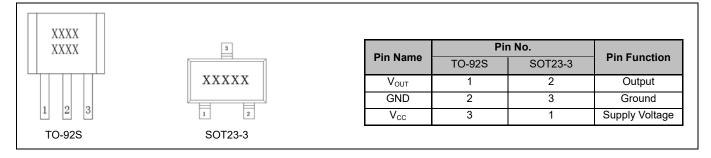


TMR1201S(Left), TMR1201T(Right)

### **Block Diagram**



# **Pin Configuration**



### **Absolute Maximum Ratings**

Parameter	Symbol	Limit	Unit	
Supply Voltage	Vcc	7	V	
Reverse Supply Voltage	V <sub>RCC</sub>	0.4	V	
Output Current	IOUTSINK	10	mA	
Magnetic Flux Density	В	1200	G	
ESD level(HBM)	V <sub>ESD</sub>	6.5	kV	
Operating Temperature	Operating Temperature T <sub>A</sub>		°C	
Storage Temperature	T <sub>stg</sub>	-50 ~ 150	°C	

# Electrical Characteristics (Vcc=3.0V, TA=25°C)

Parameter	Symbol	Conditions	Min	Тур.	Max	Unit
Supply Voltage	Vcc	Operating	1.8	3.0	5.5	V
Output High Voltage	Vон		Vcc-0.3		Vcc	V
Output Low Voltage	Vol		0		0.2	V
Supply Current	lcc	Output Open		3.4	5	μA
Response Frequency	F			1		kHz
Power-On Time	t <sub>PO</sub>			200		μs

Note: A  $0.1\mu\text{F}$  capacitor is connected between  $V_{\text{CC}}$  and GND during all tests in the above table.

Units G

G

G

BOF

BR

 $\mathbf{B}_{\mathbf{H}}$ 

Parameters	Symbol	Min	Тур.	Max	
Operate Point	Вор	10	15	20	

-15

30

35.0

30.0

25.0

20.0

15.0

10.0

5.0

0.0

-5.0

-10.0

-15.0

-40

-20

0

25

Temperature(°C)

Switch Points (G)

-10

**Temperature Performance (V<sub>CC</sub>=3.0V)** 

40

85

125

-20

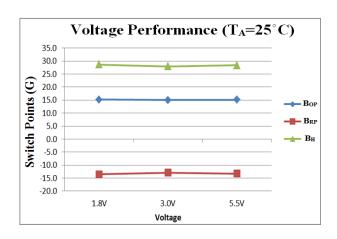
#### Magnetic Characteristics ( $V_{CC} = 3.0V$ , $T_A = 25^{\circ}C$ )

#### **Voltage and Temperature Characteristics**

Brp Bh

**Release** Point

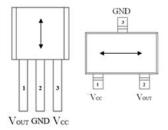
Hysteresis



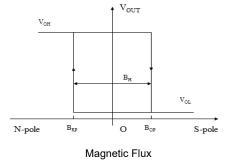
#### **Output Behavior vs. Magnetic Pole**

Parameter	Test Conditions	Output
South Pole	B > B <sub>OP</sub>	Low (On)
North Pole	B < B <sub>RP</sub>	High (Off)

Note: when power is turned on under zero magnetic field, the output is "High".



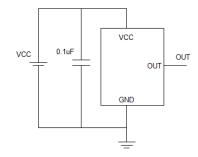
Sensing Direction of Magnetic Field



### **Application Information**

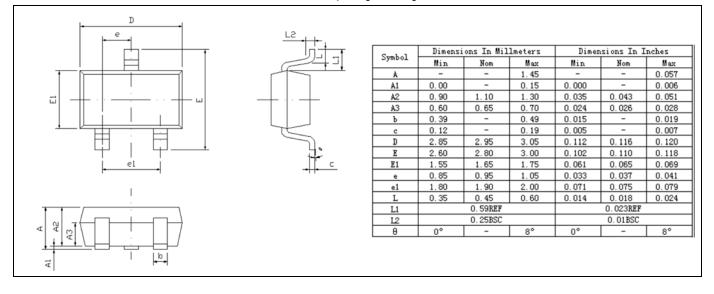
The output of the TMR1201 switches low (turns on) when a magnetic field parallel to the TMR sensor exceeds the operate point threshold,  $B_{OP}$ . When the magnetic field is reduced below the release point,  $B_{RP}$ , the device output goes high (turns off). The differences between the magnetic operate point and release point is the hysteresis  $B_H$  of the device.

It is strongly recommended that an external bypass capacitor be connected in close proximity to the device between the supply and ground to reduce noise and improve switching accuracy. The typical value of the external capacitor is  $0.1\mu$ F.

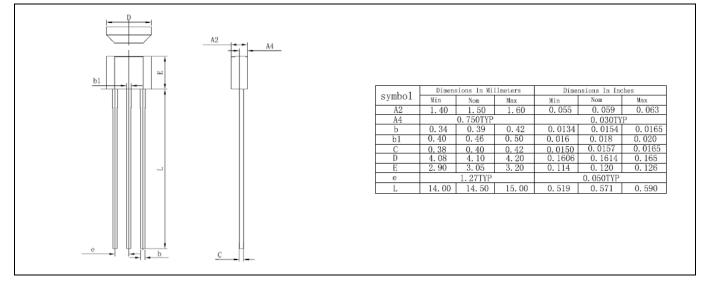


## **Package Information**

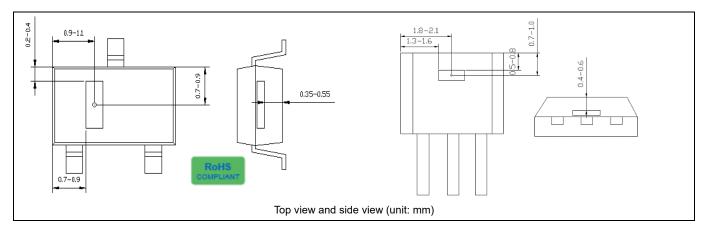
#### SOT23-3 package drawing



TO-92S package drawing



### **TMR Sensor Position**





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